# Debug a paper robot

**Where does an instruction sequence first stop matching its goal?**

## The starting state

Mark the start square, facing direction, goal and blocked square.

## My first trace

After each command, record square and direction. Where does the first blocked move occur?

## My repair

Write a new sequence and trace it from the original starting state.

## What I have checked

State what the trace demonstrates. Name one changed starting case I have not checked.

Keep it, change it or leave it here. Sharing is optional.